Remote Electrical Tilt
AISG-ST-RET
vRET3.1.5.2

Revision History

DATE	ISSUE	NOTES
31st January 2022	vRET3.1.5.2	Fourth public release
11th June 2019	vRET3.1.3.0	Third public release
27th May 2019	vRET3.1.2.1	Second public release
5th November 2018	vRET3.1.1.7	First public release

1. FOREWORD (Informative)

This standard has been produced by the Antenna Interface Standards Group (AISG) to introduce and define new features and enhancement of the management system for antenna line devices (ALDs) with remote control and monitoring facilities. AISG v3.0 base standard describes the common behaviour of antenna line devices with AISG interfaces and type-specific functionality is defined in subunit type standards. This subunit type standard covers the antenna line devices capable of altering the electrical downtilt of an antenna.

This standard is independent of previous 3GPP specifications.

2. SCOPE (Informative)

AISG v3.0 specifies the standard data interface between a primary, typically a base station, and antenna line devices (ALDs) which are manageable units, usually associated with base station antennas.

The standard is divided into the base standard and several subunit type standards. This subunit type standard document describes the specific behaviour of the Remote Electrical Tilt (RET) subunit type.

This standard defines the functional behaviour of RET subunits.

2.2 Interpretation (Normative)

The text of the standard defines explicitly what is required or permitted. Anything that is not explicitly allowed is not permitted.

All statements in this document are normative, unless indicated as informative, notes or as an example.

For purposes of compliance and AISG interoperability, users should note that the implementation of this subunit type standard is optional. However, once it is selected for inclusion in a product, the entire standard becomes mandatory.

3. REFERENCES

This AISG Standard incorporates provisions from other publications. These are cited in the text and the referenced publications are listed below. Where references are listed with a specific version or release, subsequent amendments or revisions of these publications apply only when specifically incorporated by amendment or revision of this AISG standard. For references listed without a version or release, the latest edition of the publication referred to applies.

1 AISG v3.0: “Base Standard AISG v3.0”

2 AISG v3.0 STCM: “Subunit Type Compliance Matrix”

4. VERSION COMPLIANCE (Informative)

The compliance of this standard with different version of AISG v3 baseline standard is defined in [2].

5. ABBREVIATIONS (Informative)

Where abbreviations or acronyms are used in this document they have the following meanings:

ALD	Antenna Line Device
DC	Direct Current
MALD	Multi-primary ALD
RET	Remote Electrical Tilt
SALD	Single-primary ALD
TCC	Time-Consuming Command
3GPP	3rd Generation Partnership Project

6. TERMINOLOGY

Where the following terms are used in this document, they have the following meanings:

Calibrated by design	Device is designed in such a way that it neither needs nor allows user initiated calibration.
Configured by design	Device is designed in such a way that it neither needs nor allows configuration with a configuration file.
Electrical tilt	The electrical tilt angle is, in the vertical cut, the angle between the antenna mechanical boresight and the half-power beam axis. Positive tilt values represent main beam position below boresight. Negative tilt values represent main beam position above boresight.
Half-power beam axis	The half-power beamwidth is, in a radiation pattern cut containing the beam peak axis, the angle between the two closest directions in which the radiation intensity is one-half the maximum value; its bisect is called half-power beam axis.
Mechanical boresight	The axis perpendicular with the antenna aperture.
Jam	A condition in which actuator movement is not possible.

7. DEFINITIONS

```
uint16_t RETMovementCommandPort

CONSTANT uint16_t NrOfSubunitAlarms ← 0 // Number of subunit alarm types for this
subunit type
```

NOTE: The common alarms applicable to a RET are defined in [1], because they are also applicable to other subunit types.

```
uint16_t NrOfRETSubunits// number of RET subunits within the ALD
```

8. GENERAL ASPECTS

8.1. Subunit relationship

A RET subunit has a functional relationship with one or more port(s) of the ALD as defined in [1]. In addition, a RET subunit has a functional relationship with one or more array element(s).

8.2. Control of array elements

A array element is a basic building block of an antenna, defined in [1]. Array elements are identified by an array element number. This numbering scheme is vendor specific.

One RET subunit can control multiple array elements.

8.3. State models

8.3.1. Subunit Calibration State model for layer 7

The subunit calibration state model in figure 8.3.1-1 “RETCalState state model” shows the transition between calibration states for a RET subunit.

In certain implementations, a DC power cycle during actuator movement may cause unknown position. In this circumstance the RET shall enter RETNotCalibratedState.

In RETs that support downloading ConfigurationFile and are not Calibrated by design, the successful completion of download of file type ConfigurationFile or reception of RecoverFactoryConfiguration command (see [1]) shall cause the RET to enter the RETNotCalibratedState.

This state shall be retained through a DC power cycle.

```
Enumeration RETCalState_t : uint8_t {
     RETNotCalibratedState     ← 0
     RETCalibratedState        ← 1
}

PERSISTENT RETCalState_t RETCalState[1..NrOfRETSubunits]
```

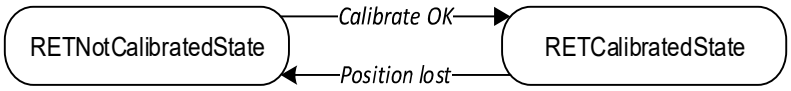

Figure 8.3.1-1 RETCalState state model

8.3.2. Subunit Jam State model for layer 7

The subunit jam state model in figure 8.3.2-1 “RETJamState state model” shows the transition between jam states for a RET subunit.

```
Enumeration RETJamState_t : uint8_t {
     RETNotJammedState    ← 0
     RETJammedState       ← 1
}
Enumeration RETJamState_t RETJamState[1..NrOfRETSubunits]
```

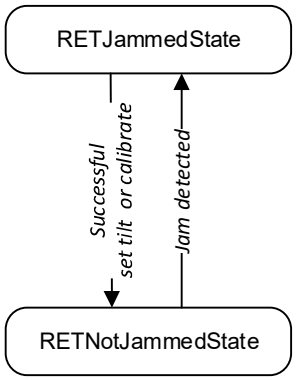

Figure 8.3.2-1 RETJamState state model

8.3.3. RET Movement State model for layer 7

The RET Movement state model in figure 8.3.3-1 ”RETMovement state model” shows the transition between actuator movement states that are common for all RET subunits in an ALD.

```
Enumeration RETMovementState_t : uint8_t {
     RETNotMovingState    ← 0
     RETMovingState       ← 1
}

RETMovementState_t RETMovementState[1..NrOfRETSubunits]
```

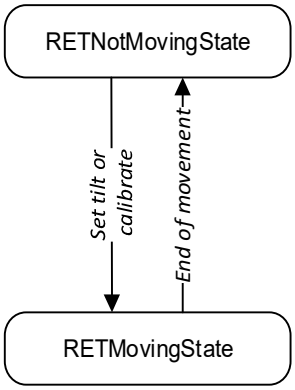

Figure 8.3.3-1 RETMovement state model

8.4. RET capabilities

The RETCapabilities bitfield is set by design.

```
Bitfield RETCapabilities_t : uint8_t {
     GetTiltDuringSetTilt           : Bit 0
     CalibratedByDesign             : Bit 1
     ConfiguredByDesign             : Bit 2
}
```

```
RETCapabilities_t RETCapabilities
```

8.5. Reset

On reset the persistent alarms are raised.

```
ON Reset DO
    FOREACH I FROM 1 TO NrOfRETSubunits DO
        IF RETJamState[I] = RETJammedState THEN
            RAISE AlarmActuatorJammed SEVERITY Major ON SUBUNIT I
        ENDIF
        UNLESS RETCapabilities.CalibratedByDesign THEN
            IF RETCalState[I] = RETNotCalibratedState THEN
                RAISE AlarmNotCalibrated SEVERITY Major ON SUBUNIT I
            ENDIF
        ENDIF
    DONE
DONE
```

The tilt angle shall be nonvolatile through reset and DC power cycle.

8.6. Actuator movement

This pseudocode defines requirements that must be met all the time during the movement by the implementation specific actuator movement code.

```
ON «position lost» DO // Position lost detection is vendor specific
    SWITCH RETCalState TO RETNotCalibratedState
    RAISE AlarmNotCalibrated SEVERITY Major ON Cmd.Subunit
    UNLESS RETCapabilities.CalibratedByDesign THEN
        // Replace “Hardware error” with descriptive text to be read using
        // GetDiagnosticInformation
        RAISE AlarmGeneralError SEVERITY Major ON Cmd.Subunit, “Hardware error”
    ENDIF
DONE

ON «jam detected» DO        // Jam detection is vendor specific
    SWITCH RETJamState TO RETJammedState
    RAISE AlarmActuatorJammed SEVERITY Major ON Cmd.Subunit
DONE

ON «jam recovered» DO
    SWITCH RETJamState TO RETNotJammedState
    CLEAR AlarmActuatorJammed SEVERITY Major ON Cmd.Subunit
DONE

// Management of DC power mode following jam recovery is implementation specific

ON «movement timeout occurred» DO
    RAISE AlarmMovementTimeout SEVERITY Minor ON Cmd.Subunit
DONE
```

8.7. Return codes

This subunit type standard extends the following subunit type specific reason codes.

```
Enumeration ReturnCode_t : uint16_t {
     RETSetTiltFailed ← 0x0100
}
```

8.8. RET configuration

Not all RET subunits require configuration. For those which do, vendor specific data is contained within the ALD configuration (see [1]). RET configuration data may include parameters used to convert electrical tilt values to actuator position and may be specific to particular combinations of actuators and antenna models. RET configuration data shall not be used in place of commands defined in AISG v3.0 standards.

The configuration data is protected as in table 8.8-1 Configuration data protection.

Configuration method	Recovered configuration	Can be overwritten by
Permanently factory configured	Not supported	Nothing
Factory configured	Factory	File or Auto
Auto-configured	Auto	File
Not factory configured	Empty	File

Table 8.8-1: Configuration data protection

NOTE: Auto-configuration is a vendor specific method, in which the antenna contains configuration data which allows the RET to be automatically configured. Auto-configuration shall take place on after a reset.

8.9. Resumption of operation

The following data shall be retained after reset:

- Configuration file (if applicable)
- Vendor specific calibration details (if applicable)
- Calibration state
- Tilt value
- Assignment of array element numbers to RET subunit(s)

9. LAYER 1

All definitions and specifications for ALDs in [1] regarding layer 1 shall be valid for ALDs which contain RET subunits.

9.1. DC power consumption

This subunit type standard does not define the power consumption of a RET. This subunit type standard contains two commands, RET Set Tilt and RET Calibrate, which allow the ALD to switch from SteadyStatePowerMode to HighPowerMode.

10. LAYER 2

All definitions and specifications for ALDs in [1] regarding layer 2 shall be valid for ALDs which contain RET subunits.

11. LAYER 7

An ALD which contains RET subunit(s) shall support the command set which is defined in [1] in addition to those commands specified in this standard.

11.1. Subunit type

Subunit type	1-octet unsigned integer code
RET	0x01

Table 11.1-1: Subunit type code

11.2. Overview of commands for RET subunits

The table below shows an overview of all commands used in this RET subunit type standard.

The following abbreviations are used in the Table 11.2-1: “Commands for RET subunits”

M Mandatory

O Optional

- Not applicable

	Code	Initiator	Subunit	Timeout	TCC	Mandatory for:			Changes the ConnectionState	Changes to HighPowerMode	Minimum require authority
						Primary	SALD	MALD			
RET commands											
RET Calibrate	0x0100	Primary	>0	4 min	yes	M	M	M	no	yes	RW
RET Set Tilt	0x0101	Primary	>0	2 min	yes	M	M	M	no	yes	RW
RET Get Tilt	0x0102	Primary	>0	1 s	no	M	M	M	no	no	RO
RET Get Capabilities	0x0103	Primary	>0	1 s	no	M	M	M	no	no	RO
Site mapping command for RET											
RET Set Array Element Numbers To Subunit	0x0104	Primary	>0	1 s	no	O	M	M	no	no	RW
RET Get Array Element Numbers From Subunit	0x0105	Primary	>0	1 s	no	O	M	M	no	no	RO

Table 11.2-1: Commands for RET subunits

11.3. Tilt representation

The tilt range supported is from −90.0° to +90.0°. The tilt value is expressed in 0.1° units with a range of −900 to +900.

The tilt accuracy of the actual beam is not defined.

11.4. RET commands

11.4.1. RET Calibrate

Description (Informative):

The calibration command triggers a process during which internal representation of tilt angles is aligned with the physical position of the elevation beam. Some RETs, for example those with absolute position encoders, are intrinsically calibrated and do not require the calibration process to be performed.

Message format:

The tilt angle on completion of the RET Calibrate command is vendor specific, so to ensure the correct tilt setting the primary shall perform the RET Set Tilt command once the calibration is completed.

```
PrimaryCommand RETCalibrateCommand {
      CommandCode_t         Command ← 0x0100
      CommandSequence_t     PrimaryCommandSequence
      Subunit_t             Subunit
      DataLength_t          DataLength ← 0
}

ALDResponse RETCalibrateResponse {
      CommandCode_t         Command ← 0x0100
      CommandSequence_t     PrimaryCommandSequence
      ReturnCode_t          ReturnCode
      DataLength_t          DataLength
      if (ReturnCode == OK) {
      }
      else {
            ALDState_t            ALDState
            ConnectionState_t     ConnectionState
            RETCalState_t         RETCalState
            RETJamState_t         RETJamState
            RETMovementState_t    RETMovementState
      }
}

Enumeration ReturnCode_t {
      OK
      FormatError
      UnknownCommand
      Busy
      InvalidSubunitNumber
      InvalidSubunitType
      NotAuthorised
      IncorrectState
      ALDNotConfigured
      InUseByAnotherPrimary
      CalibrationNotSupported
      CalibrationFailed
}
```

Primary pseudocode:

(This section is intentionally left blank)

ALD pseudocode:

```
IF ALDState = ALDNotConfiguredState THEN
        RETURN ALDNotConfigured
        EXIT
ELSEIF RETCapabilities.CalibratedByDesign THEN // For example, uses absolute position
                                                // sensor
        RETURN CalibrationNotSupported
        EXIT
ENDIF

IF ALDType = MALD THEN

        UNLESS ActiveAuth[CurrentPort].Authority[Cmd.Subunit] = ReadWrite THEN
                RETURN NotAuthorised
                EXIT
        ENDIF

ENDIF

result ← IsCommandAllowed( LIST{        OperatingConnectionState,
                                        RestrictedConnectionState},
                                        Cmd.Command, CurrentPort)

UNLESS result.allowed THEN
        RETURN result.code
        EXIT
ENDIF

LOCK StateLock

SWITCH RETMovementState TO RETMovingState
RETMovementCommandPort ← CurrentPort
UNLOCK StateLock
«Switch electronics to consume DC power from the primary which sent the RETCalibrate
command»
SWITCH DCPowerMode TO HighPowerMode
CLEAR AlarmMovementTimeout on Cmd.Subunit
«Perform calibration»

IF «calibration fails» THEN    //Raise appropriate alarms
        RETURN CalibrationFailed
ELSE
        RETURN OK
ENDIF

SWITCH RETMovementState TO RETNotMovingState
SWITCH DCPowerMode TO SteadyStatePowerMode
CommandExit(Cmd.Command, CurrentPort)
EXIT
```

11.4.2. RET Set Tilt

Description (Informative):

On the receipt of this command the RET subunit sets the tilt of the main beam to the requested angle.

Message format:

```
PrimaryCommand RETSetTiltCommand {
      CommandCode_t         Command ← 0x0101
      CommandSequence_t     PrimaryCommandSequence
      Subunit_t             Subunit
      DataLength_t          DataLength ← 2
      int16_t                     TiltValue
}

ALDResponse RETSetTiltResponse {
      CommandCode_t         Command ← 0x0101
      CommandSequence_t     PrimaryCommandSequence
      ReturnCode_t          ReturnCode
      DataLength_t          DataLength
      if (ReturnCode == OK) {
      }
      else {
            ALDState_t            ALDState
            ConnectionState_t     ConnectionState
            RETCalState_t         RETCalState
            RETJamState_t         RETJamState
            RETMovementState_t    RETMovementState
      }
}

Enumeration ReturnCode_t {
      OK
      FormatError
      UnknownCommand
      Busy
      InvalidSubunitNumber
      InvalidSubunitType
      NotAuthorised
      IncorrectState
      InUseByAnotherPrimary
      NotCalibrated
      ALDNotConfigured
      OutOfRange
      RETSetTiltFailed
}
```

Primary pseudocode:

(This section is intentionally left blank)

ALD pseudocode:

```
IF «the requested tilt angle is not supported» THEN
        RETURN OutOfRange
        EXIT
ELSEIF ALDState = ALDNotConfiguredState THEN
        RETURN ALDNotConfigured
        EXIT
ELSEIF RETCalState = RETNotCalibratedState THEN
        RETURN NotCalibrated
        EXIT
ENDIF

IF ALDType = MALD THEN
        UNLESS ActiveAuth[CurrentPort].Authority[Cmd.Subunit] = ReadWrite THEN
                RETURN NotAuthorised
                EXIT
        ENDIF
ENDIF

result ← IsCommandAllowed( LIST{        OperatingConnectionState,
                                        RestrictedConnectionState},
                                        Cmd.Command, CurrentPort)

UNLESS result.allowed THEN
        RETURN result.code
        EXIT
ENDIF

LOCK StateLock

SWITCH RETMovementState TO RETMovingState
RETMovementCommandPort ← CurrentPort
UNLOCK StateLock
«Switch electronics to consume DC power from the primary which requests tilting»
SWITCH DCPowerMode TO HighPowerMode
CLEAR AlarmMovementTimeout on Cmd.Subunit
«Perform tilt change»

IF «tilt setting fails» THEN     // Raise appropriate alarms
        RETURN RETSetTiltFailed
ELSE
        RETURN OK
ENDIF

SWITCH RETMovementState TO RETNotMovingState
SWITCH DCPowerMode TO SteadyStatePowerMode
CommandExit(Cmd.Command, CurrentPort)
EXIT
```

11.4.3. RET Get Tilt

Description (Informative):

On the receipt of this command the RET subunit shall return the current electrical tilt value.

Message format:

```
PrimaryCommand RETGetTiltCommand {
      CommandCode_t         Command ← 0x0102
      CommandSequence_t     PrimaryCommandSequence
      Subunit_t             Subunit
      DataLength_t          DataLength ← 0
}

ALDResponse RETGetTiltResponse {
      CommandCode_t         Command ← 0x0102
      CommandSequence_t     PrimaryCommandSequence
      ReturnCode_t          ReturnCode
      DataLength_t          DataLength
      if (ReturnCode == OK) {
            int16_t         TiltValue
      }
      else {
            ALDState_t            ALDState
            ConnectionState_t     ConnectionState
            RETCalState_t         RETCalState
            RETJamState_t         RETJamState
            RETMovementState_t    RETMovementState
      }
}

Enumeration ReturnCode_t{
      OK
      FormatError
      UnknownCommand
      Busy
      InvalidSubunitNumber
      InvalidSubunitType
      NotAuthorised
      IncorrectState
      NotCalibrated
      ALDNotConfigured
}
```

Primary pseudocode):

(This section is intentionally left blank)

ALD pseudocode:

```
IF ALDType = MALD THEN
      IF ActiveAuth[CurrentPort].Authority[Cmd.Subunit] = NoAccess THEN
            RETURN NotAuthorised
            EXIT
      ENDIF
```

```
ENDIF
result ← IsCommandAllowed( LIST{    OperatingConnectionState,
                                    RestrictedConnectionState},
                                    Cmd.Command, CurrentPort)
UNLESS result.allowed THEN
      RETURN result.code
      EXIT
ENDIF
IF ALDState = ALDNotConfiguredState THEN
      RETURN ALDNotConfigured
ELSEIF RETCalState = RETNotCalibratedState THEN
      RETURN NotCalibrated
ELSE
      RETURN OK, «current tilt value»
ENDIF
CommandExit(Cmd.Command, CurrentPort)
EXIT
```

11.4.4. RET Get Capabilities

Description (Informative):

On the receipt of this command the RET subunit returns the RET capabilities:

- Whether or not it is possible to query the tilt during a RET Set Tilt command
- Whether or not it is calibrated by design
- Whether or not it is configured by design
- Supported electrical tilt range

Primaries should use this command whenever the ALD has performed a reset and whenever the RET has been configured (if supported).

Message format:

```
PrimaryCommand RETGetCapabilitiesCommand {
     CommandCode_t         Command ← 0x0103
     CommandSequence_t     PrimaryCommandSequence
     Subunit_t             Subunit
     DataLength_t          DataLength ← 0
}
```

```
ALDResponse RETGetCapabilitiesResponse {
      CommandCode_t         Command ← 0x0103
      CommandSequence_t     PrimaryCommandSequence
      ReturnCode_t          ReturnCode
      DataLength_t          DataLength
      if (ReturnCode == OK) {
            int16_t         MinTiltRange
            int16_t         MaxTiltRange
            RETCapabilities_t RETCapabilities
      }
      else {
            ALDState_t            ALDState
            ConnectionState_t     ConnectionState
            RETCalState_t         RETCalState
            RETJamState_t         RETJamState
            RETMovingState_t      RETMovementState
      }
}

Enumeration ReturnCode_t {
      OK
      FormatError
      UnknownCommand
      Busy
      InvalidSubunitNumber
      InvalidSubunitType
      NotAuthorised
      IncorrectState
}
```

Primary pseudocode:

(This section is intentionally left blank)

ALD pseudocode:

```
IF ALDType = MALD
      AND ActiveAuth[CurrentPort].Authority[Cmd.Subunit] = NoAccess THEN
      RETURN NotAuthorised
      EXIT
ENDIF

result ← IsCommandAllowed( LIST{      OperatingConnectionState
                                      RestrictedConnectionState,
                                      MALDSetupConnectionState},
                                      Cmd.Command, CurrentPort)

UNLESS result.allowed THEN
      RETURN result.code
      EXIT
ENDIF

RETURN OK, «tilt range and table of capabilities»
CommandExit(Cmd.Command, CurrentPort)
EXIT
```

11.4.5. RET Set Array Element Numbers To Subunit

Description (Informative):

This command stores a provided list of array element numbers the subunit is controlling.

The ALD vendor may have defined one or more array element number as read only. In that case the array element numbers are not stored and the ALD will return the DataReadOnly return code.

Message format:

```
PrimaryCommand RETSetArrayElementNumbersToSubunitCommand {
      CommandCode_t         Command ← 0x0104
      CommandSequence_t     PrimaryCommandSequence
      Subunit_t             Subunit
      DataLength_t          DataLength
      uint8_t               NrOfArrayElements
      uint16_t              ArrayElementNumbers[1..NrOfArraysElements]
      Provenance_t          ArrayElementNumbersProvenance   // Provenance manual
                                                            // indicates that the
                                                            // ArrayElementNumbers
                                                            // has been supplied by the
                                                            // user. Automatic
                                                            // indicates that primary
                                                            // has assigned it with an
                                                            // automated algorithm.
}

ALDResponse RETSetArrayElementNumbersToSubunitResponse {
      CommandCode_t         Command ← 0x0104
      CommandSequence_t     PrimaryCommandSequence
      ReturnCode_t          ReturnCode
      DataLength_t          DataLength
      if (ReturnCode == OK) {
      }
      else {
            ALDState_t            ALDState
            ConnectionState_t     ConnectionState
            RETCalState_t         RETCalState
            RETJamState_t         RETJamState
            RETMovingState_t      RETMovementState
      }
}

Enumeration ReturnCode_t {
      OK
      FormatError
      UnknownCommand
      Busy
      IncorrectState
      InvalidSubunitNumber
      InvalidSubunitType
      NotAuthorised
      DataReadOnly
      InvalidArrayElementNumber
      GeneralError
}
```

Primary pseudocode:

(This section is intentionally left blank)

ALD pseudocode:

```
UNLESS Cmd. ArrayElementNumber IN ArrayElementNumberList THEN
    RETURN InvalidArrayElementNumber
    EXIT
ENDIF

IF ALDType = MALD THEN

    UNLESS ActiveAuth[CurrentPort].Authority[Cmd.Subunit] = ReadWrite THEN
        RETURN NotAuthorised
        EXIT
    ENDIF

ENDIF

result ← IsCommandAllowed( LIST{    OperatingConnectionState},
                                    Cmd.Command, CurrentPort)

UNLESS result.allowed THEN
    RETURN result.code
    EXIT
ENDIF

IF «Array element numbers are read only in this RET subunit» THEN
    RETURN DataReadOnly
ELSE
    «Store the array element numbers and their provenance for the supplied Subunit to
        non-volatile memory»

    IF «the ALD detects a hardware error» THEN
        // Replace “Hardware error” with descriptive text to be read using
        // GetDiagnosticInformation
        RAISE AlarmGeneralError SEVERITY Major ON Cmd.Subunit, “Hardware error”
        RETURN GeneralError
    ELSE
        RETURN OK
    ENDIF
ENDIF

CommandExit(Cmd.Command, CurrentPort)
EXIT
```

11.4.6. RET Get Array Element Numbers From Subunit

Description (Informative):

This command returns the list of array elements the subunit is controlling.

Message format:

```
PrimaryCommand RETGetArrayElementNumbersFromSubunitCommand {
      CommandCode_t         Command ← 0x0105
      CommandSequence_t     PrimaryCommandSequence
      Subunit_t             Subunit
      DataLength_t          DataLength ← 0
}

ALDResponse RETGetArrayElementNumbersFromSubunitResponse {
      CommandCode_t         Command ← 0x0105
      CommandSequence_t     PrimaryCommandSequence
      ReturnCode_t          ReturnCode
      DataLength_t          DataLength
      if (ReturnCode == OK) {
            uint8_t         NrOfArrayElements
            uint16_t        ArrayElementNumber[1..NrOfArrayElements]
            Provenance_t    ArrayElementNumbersProvenance
      }
      else {
            ALDState_t            ALDState
            ConnectionState_t     ConnectionState
            RETCalState_t         RETCalState
            RETJamState_t         RETJamState
            RETMovingState_t      RETMovementState
      }
}

Enumeration ReturnCode_t {
      OK
      FormatError
      UnknownCommand
      Busy
      InvalidSubunitNumber
      InvalidSubunitType
      NotAuthorised
      IncorrectState
}
```

Primary pseudocode:

(This section is intentionally left blank)

ALD pseudocode:

```
IF ALDType = MALD
      AND ActiveAuth[CurrentPort].Authority[Cmd.Subunit] = NoAccess THEN
      RETURN NotAuthorised
      EXIT
ENDIF

result ← IsCommandAllowed( LIST{     OperatingConnectionState
                                     RestrictedConnectionState,
                                     MALDSetupConnectionState},
                                     Cmd.Command, CurrentPort)

UNLESS result.allowed THEN
      RETURN result.code
      EXIT
ENDIF
```

RETURN OK, « number of stored array elements and the list of array numbers and the provenance of requested RET Subunit»
CommandExit(Cmd.Command, CurrentPort)
EXIT