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***Remote Electrical Tilt***  
***AISG-ST-RET***  
***vRET3.1.3.0***

***Revision History***

<b>DATE</b>	<b>ISSUE</b>	<b>NOTES</b>
11 <sup>th</sup> June 2019	vRET3.1.3.0	Third public release
27 <sup>th</sup> May 2019	vRET3.1.2.1	Second public release
5 <sup>th</sup> November 2018	vRET3.1.1.7	First public release

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### vRET3.1.3.0

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## 1. FOREWORD (Informative)

This standard has been produced by the Antenna Interface Standards Group (AISG) to introduce and define new features and enhancement of the management system for antenna line devices (ALDs) with remote control and monitoring facilities. AISG v3.0 base standard describes the common behaviour of antenna line devices with AISG interfaces and type-specific functionality is defined in subunit type standards. This subunit type standard covers the antenna line devices capable of altering the electrical downtilt of an antenna.

This standard is independent of previous 3GPP specifications.

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## 2. SCOPE (Informative)

AISG v3.0 specifies the standard data interface between a primary, typically a base station, and antenna line devices (ALDs) which are manageable units, usually associated with base station antennas.

The standard is divided into the base standard and several subunit type standards. This subunit type standard document describes the specific behaviour of the Remote Electrical Tilt (RET) subunit type.

This standard defines the functional behaviour of RET subunits.

## 2.2 Interpretation (Normative)

The text of the standard defines explicitly what is required or permitted. Anything that is not explicitly allowed is not permitted.

All statements in this document are normative, unless indicated as informative, notes or as an example.

For purposes of compliance and AISG interoperability, users should note that the implementation of this subunit type standard is optional. However, once it is selected for inclusion in a product, the entire standard becomes mandatory.

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### 3. REFERENCES

This AISG Standard incorporates provisions from other publications. These are cited in the text and the referenced publications are listed below. Where references are listed with a specific version or release, subsequent amendments or revisions of these publications apply only when specifically incorporated by amendment or revision of this AISG standard. For references listed without a version or release, the latest edition of the publication referred to applies.

- 1 AISG v3.0: "Base Standard AISG v3.0"
- 2 AISG v3.0 STCM: "Subunit Type Compliance Matrix"

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**4. VERSION COMPLIANCE (Informative)**

The compliance of this standard with different version of AISG v3 baseline standard is defined in [2].

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## 5. ABBREVIATIONS (Informative)

Where abbreviations or acronyms are used in this document they have the following meanings:

ALD	Antenna Line Device
DC	Direct Current
MALD	Multi-primary ALD
RET	Remote Electrical Tilt
SALD	Single-primary ALD
TCC	Time-Consuming Command
3GPP	3 <sup>rd</sup> Generation Partnership Project



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## **6. TERMINOLOGY**

Where the following terms are used in this document, they have the following meanings:

Calibrated by design	Intrinsically calibrated, does not allow user initiated calibration.
Electrical tilt	The electrical tilt angle is, in the vertical cut, the angle between the antenna mechanical boresight and the half-power beam axis. Positive tilt values represent main beam position below boresight. Negative tilt values represent main beam position above boresight.
Half-power beam axis	The half-power beamwidth is, in a radiation pattern cut containing the beam peak axis, the angle between the two closest directions in which the radiation intensity is one-half the maximum value; its bisect is called half-power beam axis.
Mechanical boresight	The axis perpendicular with the antenna aperture.
Jam	A condition in which actuator movement is not possible.

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## 7. DEFINITIONS

```
uint16_t RETMovementCommandPort
```

```
CONSTANT uint16_t NrOfSubunitAlarms ← 0 // Number of subunit alarm types for this  
subunit type
```

**NOTE:** The common alarms applicable to a RET are defined in [1], because they are also applicable to other subunit types.

```
uint16_t NrOfRETSubunits // number of RET subunits within the ALD
```



## 8. GENERAL ASPECTS

### 8.1. Subunit relationship

A RET subunit has a functional relationship with one or more port(s) of the ALD as defined in [1]. In addition, a RET subunit has a functional relationship with one or more logical array(s).

### 8.2. Control of logical arrays

A logical array is a basic array element of an antenna, defined in [1]. Logical arrays are identified by a logical array number. This numbering scheme is vendor specific.

One RET subunit can control multiple logical arrays.

### 8.3. State models

#### 8.3.1. Subunit Calibration State model for layer 7

The subunit calibration state model in figure 8.3.1-1 “RETCalState state model” shows the transition between calibration states for a RET subunit.

In certain implementations, a DC power cycle during actuator movement may cause unknown position. In this circumstance the RET shall enter RETNotCalibratedState.

In RETs that support downloading ConfigurationFile and are not CalibratedByDesign, the successful completion of download of file type ConfigurationFile or reception of RecoverFactoryConfiguration command (see [1]) shall cause the RET to enter the RETNotCalibratedState.

This state shall be retained through a DC power cycle.

```
Enumeration RETCalState_t : uint8_t {  
    RETNotCalibratedState ← 0  
    RETCalibratedState ← 1  
}  
  
PERSISTENT RETCalState_t RETCalState[1..NrOfRETSubunits]
```

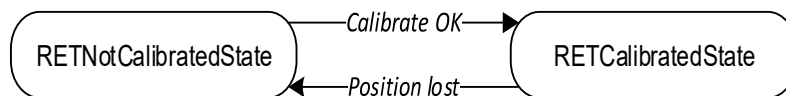


Figure 8.3.1-1 RETCalState state model

#### 8.3.2. Subunit Jam State model for layer 7

The subunit jam state model in figure 8.3.2-1 “RETJamState state model” shows the transition between jam states for a RET subunit.

```
Enumeration RETJamState_t : uint8_t {  
    RETNotJammedState ← 0  
    RETJammedState ← 1  
}  
  
Enumeration RETJamState_t RETJamState[1..NrOfRETSubunits]
```

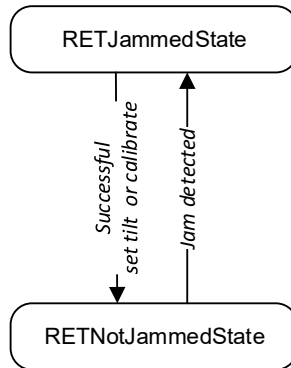


Figure 8.3.2-1 RETJamState state model

### 8.3.3. RET Movement State model for layer 7

The RET Movement state model in figure 8.3.3-1 "RETMovement state model" shows the transition between actuator movement states that are common for all RET subunits in an ALD.

```

Enumeration RETMovementState_t : uint8_t {
    RETNotMovingState ← 0
    RETMovingState ← 1
}

RETMovementState_t RETMovementState[1..NrOfRETSubunits]
  
```

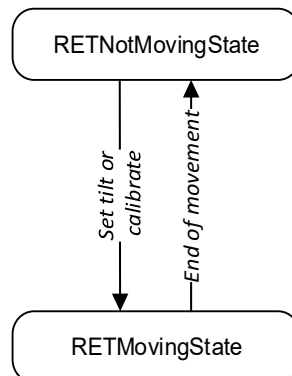


Figure 8.3.3-1 RETMovement state model

## 8.4. RET capabilities

The RETCapabilities bitfield is set by design.

```

Bitfield RETCapabilities_t : uint8_t {
    GetTiltDuringSetTilt : Bit 0
    CalibratedByDesign : Bit 1
    ConfiguredByDesign : Bit 2
}
  
```

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RETCapabilities\_t RETCapabilities

## 8.5. Reset

On reset the persistent alarms are raised.

```
ON Reset DO
  FOREACH I FROM 1 TO NrofRETSubunits DO
    IF RETJamState[I] = RETJammedState THEN
      RAISE AlarmActuatorJammed SEVERITY Major ON SUBUNIT I
    ENDIF
    UNLESS RETCapabilities.CalibratedByDesign THEN
      IF RETCalState[I] = RETNotCalibratedState THEN
        RAISE AlarmNotCalibrated SEVERITY Major ON SUBUNIT I
      ENDIF
    ENDIF
  DONE
DONE
```

The tilt angle shall be nonvolatile through reset and DC power cycle.

## 8.6. Actuator movement

This pseudocode defines requirements that must be met all the time during the movement by the implementation specific actuator movement code.

```
ON «position lost» DO // Position lost detection is vendor specific
  SWITCH RETCalState TO RETNotCalibratedState
  RAISE AlarmNotCalibrated SEVERITY Major ON Cmd.Subunit
  UNLESS RETCapabilities.CalibratedByDesign THEN
    // Replace "Hardware error" with descriptive text to be read using
    // GetDiagnosticInformation
    RAISE AlarmGeneralError SEVERITY Major ON Cmd.Subunit, "Hardware error"
  ENDIF
DONE

ON «jam detected» DO // Jam detection is vendor specific
  SWITCH RETJamState TO RETJammedState
  RAISE AlarmActuatorJammed SEVERITY Major ON Cmd.Subunit
DONE

ON «jam recovered» DO
  SWITCH RETJamState TO RETNotJammedState
  CLEAR AlarmActuatorJammed SEVERITY Major ON Cmd.Subunit
DONE

// Management of DC power mode following jam recovery is implementation specific

ON «movement timeout occurred» DO
  RAISE AlarmMovementTimeout SEVERITY Minor ON Cmd.Subunit
DONE
```

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## 8.7. Return codes

This subunit type standard extends the following subunit type specific reason codes.

```
Enumeration ReturnCode_t : uint16_t {  
    RETSetTiltFailed ← 0x0100  
}
```

## 8.8. RET configuration

Not all RET subunits require configuration. For those which do, vendor specific data is contained within the ALD configuration (see [1]). RET configuration data may include parameters used to convert electrical tilt values to actuator position and may be specific to particular combinations of actuators and antenna models. RET configuration data shall not be used in place of commands defined in AISG v3.0 standards.

The configuration data is protected as in table 8.8-1 Configuration data protection.

Configuration method	Recovered configuration	Can be overwritten by
Permanently factory configured	Not supported	Nothing
Factory configured	Factory	File or Auto
Auto-configured	Auto	File
Not factory configured	Empty	File

**Table 8.8-1: Configuration data protection**

**NOTE:** Auto-configuration is a vendor specific method, in which the antenna contains prestored configuration data, which allows the RET to be automatically configured. Auto-configuration shall take place on after a reset.

## 8.9. Resumption of operation

The following data shall be retained after reset:

- Configuration file (if applicable)
- Vendor specific calibration details (if applicable)
- Calibration state
- Tilt value
- Assignment of logical array numbers to RET subunit(s)

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## 9. LAYER 1

All definitions and specifications for ALDs in [1] regarding layer 1 shall be valid for ALDs which contain RET subunits.

### 9.1. DC power consumption

This subunit type standard does not define the power consumption of a RET. This subunit type standard contains two commands, RET Set Tilt and RET Calibrate, which allow the ALD to switch from SteadyStatePowerMode to HighPowerMode.

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**10. LAYER 2**

All definitions and specifications for ALDs in [1] regarding layer 2 shall be valid for ALDs which contain RET subunits.



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## 11. LAYER 7

An ALD which contains RET subunit(s) shall support the command set which is defined in [1] in addition to those commands specified in this standard.

### 11.1. Subunit type

<b>Subunit type</b>	<b>1-octet unsigned integer code</b>
RET	0x01

**Table 11.1-1: Subunit type code**

### 11.2. Overview of commands for RET subunits

The table below shows an overview of all commands used in this RET subunit type standard.

The following abbreviations are used in the Table 11.2-1: “Commands for RET subunits”

- M Mandatory
- O Optional
- Not applicable

	Code	Initiator	Subunit	Timeout	TCC	Mandatory for:			Changes the ConnectionState	Changes to HighPowerMode	Minimum require authority
						Primary	SALD	MALD			
<b>RET commands</b>											
RET Calibrate	0x0100	Primary	>0	4 min	yes	M	M	M	no	yes	RW
RET Set Tilt	0x0101	Primary	>0	2 min	yes	M	M	M	no	yes	RW
RET Get Tilt	0x0102	Primary	>0	1 s	no	M	M	M	no	no	RO
RET Get Capabilities	0x0103	Primary	>0	1 s	no	M	M	M	no	no	RO
<b>Site mapping command for RET</b>											
RET Set Logical Array Numbers To Subunit	0x0104	Primary	>0	1 s	no	O	M	M	no	no	RW
RET Get Logical Array Numbers Of Subunit	0x0105	Primary	>0	1 s	no	O	M	M	no	no	RO

**Table 11.2-1: Commands for RET subunits**

### 11.3. Tilt representation

The tilt range supported is from  $-90.0^\circ$  to  $+90.0^\circ$ . The tilt value is expressed in  $0.1^\circ$  units with a range of  $-900$  to  $+900$ .

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The tilt accuracy of the actual beam is not defined.

## 11.4. RET commands

### 11.4.1. RET Calibrate

#### Description (Informative):

The calibration command triggers a process during which internal representation of tilt angles is aligned with the physical position of the elevation beam. Some RETs, for example those with absolute position encoders, are intrinsically calibrated and do not require the calibration process to be performed.

#### Message format:

The tilt angle on completion of the RET Calibrate command is vendor specific, so to ensure the correct tilt setting the primary shall perform the RET Set Tilt command once the calibration is completed.

```
PrimaryCommand RETCalibrateCommand {
    CommandCode_t      Command ← 0x0100
    CommandSequence_t  PrimaryCommandSequence
    Subunit_t          Subunit
    DataLength_t       DataLength ← 0
}

ALDResponse RETCalibrateResponse {
    CommandCode_t      Command ← 0x0100
    CommandSequence_t  PrimaryCommandSequence
    ReturnCode_t       ReturnCode
    DataLength_t       DataLength
    if (ReturnCode == OK) {
    }
    else {
        ALDState_t      ALDState
        ConnectionState_t  ConnectionState
        RETCalState_t    RETCalState
        RETJamState_t    RETJamState
        RETMovementState_t  RETMovementState
    }
}

Enumeration ReturnCode_t {
    OK
    FormatError
    UnknownCommand
    Busy
    InvalidSubunitNumber
    InvalidSubunitType
    NotAuthorised
    IncorrectState
    ALDNotConfigured
    InUseByAnotherPrimary
    CalibrationNotSupported
    CalibrationFailed
}
```

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#### Primary pseudocode:

*(This section is intentionally left blank)*

#### ALD pseudocode:

```
IF ALDState = ALDNotConfiguredState THEN
    RETURN ALDNotConfigured
    EXIT
ELSEIF RETCapabilities.CalibratedByDesign THEN // For example, uses absolute position
                                                // sensor
    RETURN CalibrationNotSupported
    EXIT
ENDIF
IF ALDType = MALD THEN
    UNLESS ActiveAuth[CurrentPort].Authority[Cmd.Subunit] = ReadWrite THEN
        RETURN NotAuthorised
        EXIT
    ENDIF
ENDIF
result ← IsCommandAllowed( LIST{      OperatingConnectionState,
                                     RestrictedConnectionState},
                           Cmd.Command, CurrentPort)
UNLESS result.allowed THEN
    RETURN result.code
    EXIT
ENDIF
LOCK StateLock
IF RETMovementState = RETMovingState THEN
    IF RETMovementCommandPort = CurrentPort THEN // TCC from same primary
        RETURN Busy
    ELSE
        RETURN InUseByAnotherPrimary // TCC from other primary
    ENDIF
    UNLOCK StateLock
    CommandExit(Cmd.Command, CurrentPort)
    EXIT
ENDIF
SWITCH RETMovementState TO RETMovingState
RETMovementCommandPort ← CurrentPort
UNLOCK StateLock
«Switch electronics to consume DC power from the primary which sent the RETCalibrate
command»
```

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```
SWITCH DCPowerMode TO HighPowerMode
CLEAR AlarmMovementTimeout on Cmd.Subunit
«Perform calibration»
```

```
IF «calibration fails» THEN //Raise appropriate alarms
    RETURN CalibrationFailed
ELSE
    RETURN OK
ENDIF
```

```
SWITCH RETMovementState TO RETNotMovingState
SWITCH DCPowerMode TO SteadyStatePowerMode
CommandExit(Cmd.Command, CurrentPort)
EXIT
```

#### 11.4.2. RET Set Tilt

##### Description (Informative):

On the receipt of this command the RET subunit sets the tilt of the main beam to the requested angle.

##### Message format:

```
PrimaryCommand RETSetTiltCommand {
    CommandCode_t      Command ← 0x0101
    CommandSequence_t  PrimaryCommandSequence
    Subunit_t          Subunit
    DataLength_t       DataLength ← 2
    int16_t            TiltValue
}

ALDResponse RETSetTiltResponse {
    CommandCode_t      Command ← 0x0101
    CommandSequence_t  PrimaryCommandSequence
    ReturnCode_t       ReturnCode
    DataLength_t       DataLength
    if (ReturnCode == OK) {
    }
    else {
        ALDState_t      ALDState
        ConnectionState_t  ConnectionState
        RETCalState_t   RETCalState
        RETJamState_t   RETJamState
        RETMovementState_t  RETMovementState
    }
}
```

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```
Enumeration ReturnCode_t {
    OK
    FormatError
    UnknownCommand
    Busy
    InvalidSubunitNumber
    InvalidSubunitType
    NotAuthorised
    IncorrectState
    InUseByAnotherPrimary
    NotCalibrated
    ALDNotConfigured
    OutOfRange
    RETSetTiltFailed
}
```

#### Primary pseudocode:

*(This section is intentionally left blank)*

#### ALD pseudocode:

```
IF «the requested tilt angle is not supported» THEN
    RETURN OutOfRange
    EXIT
ELSEIF ALDState = ALDNotConfiguredState THEN
    RETURN ALDNotConfigured
    EXIT
ELSEIF RETCalState = RETNotCalibratedState THEN
    RETURN NotCalibrated
    EXIT
ENDIF

IF ALDType = MALD THEN
    UNLESS ActiveAuth[CurrentPort].Authority[Cmd.Subunit] = ReadWrite THEN
        RETURN NotAuthorised
        EXIT
    ENDIF
ENDIF

result ← IsCommandAllowed( LIST{ OperatingConnectionState,
                                RestrictedConnectionState},
                           Cmd.Command, CurrentPort)

UNLESS result.allowed THEN
    RETURN result.code
    EXIT
ENDIF
```

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LOCK StateLock

IF RETMovementState = RETMovingState THEN

    IF RETMovementCommandPort = CurrentPort THEN     // TCC from same primary  
        RETURN Busy

    ELSE  
        RETURN InUseByAnotherPrimary                     // TCC from other primary

    ENDIF

UNLOCK StateLock

CommandExit(Cmd.Command, CurrentPort)

EXIT

ENDIF

SWITCH RETMovementState TO RETMovingState

RETMovementCommandPort ← CurrentPort

UNLOCK StateLock

«Switch electronics to consume DC power from the primary which requests tilting»

SWITCH DCPowerMode TO HighPowerMode

CLEAR AlarmMovementTimeout on Cmd.Subunit

«Perform tilt change»

IF «tilt setting fails» THEN     // Raise appropriate alarms

    RETURN RETSetTiltFailed

ELSE

    RETURN OK

ENDIF

SWITCH RETMovementState TO RETNotMovingState

SWITCH DCPowerMode TO SteadyStatePowerMode

CommandExit(Cmd.Command, CurrentPort)

EXIT

#### 11.4.3. RET Get Tilt

##### Description (Informative):

On the receipt of this command the RET subunit shall return the current electrical tilt value.

##### Message format:

```
PrimaryCommand RETGetTiltCommand {  
    CommandCode_t        Command ← 0x0102  
    CommandSequence_t   PrimaryCommandSequence  
    Subunit_t            Subunit  
    DataLength_t        DataLength ← 0  
}
```

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```
ALDResponse RETGetTiltResponse {
    CommandCode_t      Command ← 0x0102
    CommandSequence_t  PrimaryCommandSequence
    ReturnCode_t       ReturnCode
    DataLength_t       DataLength
    if (ReturnCode == OK) {
        int16_t        TiltValue
    }
    else {
        ALDState_t      ALDState
        ConnectionState_t  ConnectionState
        RETCalState_t   RETCalState
        RETJamState_t   RETJamState
        RETMovementState_t  RETMovementState
    }
}

Enumeration ReturnCode_t{
    OK
    FormatError
    UnknownCommand
    Busy
    InvalidSubunitNumber
    InvalidSubunitType
    NotAuthorised
    IncorrectState
    NotCalibrated
    ALDNotConfigured
}
```

#### Primary pseudocode):

*(This section is intentionally left blank)*

#### ALD pseudocode:

IF ALDType = MALD THEN

```
    IF ActiveAuth[CurrentPort].Authority[Cmd.Subunit] = NoAccess THEN
        RETURN NotAuthorised
    EXIT
ENDIF
```

ENDIF

```
result ← IsCommandAllowed( LIST{      OperatingConnectionState,
                                   RestrictedConnectionState},
                           Cmd.Command, CurrentPort)
```

```
UNLESS result.allowed THEN
    RETURN result.code
EXIT
ENDIF
```

```
IF ALDState = ALDNotConfiguredState THEN
    RETURN ALDNotConfigured
ELSEIF RETCalState = RETNotCalibratedState THEN
    RETURN NotCalibrated
```

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```
ELSE
    RETURN OK, «current tilt value»
ENDIF
CommandExit(Cmd.Command, CurrentPort)
EXIT
```

#### 11.4.4. RET Get Capabilities

##### Description (Informative):

On the receipt of this command the RET subunit returns the RET capabilities:

- Whether or not it is possible to query the tilt during a RET Set Tilt command
- Whether or not it is calibrated by design
- Whether or not it is configured by design
- Supported electrical tilt range

Primaries should use this command whenever the ALD has performed a reset and whenever the RET has been configured (if supported).

##### Message format:

```
PrimaryCommand RETGetCapabilitiesCommand {
    CommandCode_t      Command ← 0x0103
    CommandSequence_t  PrimaryCommandSequence
    Subunit_t          Subunit
    DataLength_t       DataLength ← 0
}

ALDResponse RETGetCapabilitiesResponse {
    CommandCode_t      Command ← 0x0103
    CommandSequence_t  PrimaryCommandSequence
    ReturnCode_t       ReturnCode
    DataLength_t       DataLength
    if (ReturnCode == OK) {
        int16_t         MinTiltRange
        int16_t         MaxTiltRange
        RETCapabilities_t RETCapabilities
    }
    else {
        ALDState_t      ALDState
        ConnectionState_t ConnectionState
        RETCalState_t   RETCalState
        RETJamState_t   RETJamState
        RETMovingState_t RETMovementState
    }
}

Enumeration ReturnCode_t {
    OK
    FormatError
    UnknownCommand
    Busy
    InvalidSubunitNumber
    InvalidSubunitType
    NotAuthorised
    IncorrectState
}
```



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#### Primary pseudocode:

*(This section is intentionally left blank)*

#### ALD pseudocode:

```
IF ALDType = MALD
    AND ActiveAuth[CurrentPort].Authority[Cmd.Subunit] = NoAccess THEN
        RETURN NotAuthorised
    EXIT
ENDIF

result ← IsCommandAllowed( LIST{      OperatingConnectionState
                                     RestrictedConnectionState,
                                     MALDConfigConnectionState},
                           Cmd.Command, CurrentPort)

UNLESS result.allowed THEN
    RETURN result.code
    EXIT
ENDIF

RETURN OK, «tilt range and table of capabilities»
CommandExit(Cmd.Command, CurrentPort)
EXIT
```

#### 11.4.5. RET Set Logical Array Numbers To Subunit

##### Description (Informative):

This command stores a provided list of logical array numbers the subunit is controlling.

The ALD vendor may have defined one or more logical array number as read only. In that case the logical array numbers are not stored and the command will return ReturnCode DataReadOnly.

##### Message format:

```
PrimaryCommand RETSetLogicalArrayNumbersToSubunitCommand {
    CommandCode_t      Command ← 0x0104
    CommandSequence_t  PrimaryCommandSequence
    Subunit_t          Subunit
    DataLength_t       DataLength
    uint8_t            NrOfLogicalArrays
    uint16_t           LogicalArrayNumbers[1..NrOfLogicalArrays]
}
```

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## Subunit Type Standard AISG-ST-RET

### vRET3.1.3.0

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```
ALDResponse RETSetLogicalArrayNumbersToSubunitResponse {
    CommandCode_t      Command ← 0x0104
    CommandSequence_t  PrimaryCommandSequence
    ReturnCode_t       ReturnCode
    DataLength_t       DataLength
    if (ReturnCode == OK) {
    }
    else {
        ALDState_t      ALDState
        ConnectionState_t  ConnectionState
        RETCalState_t    RETCalState
        RETJamState_t    RETJamState
        RETMovingState_t  RETMovementState
    }
}

Enumeration ReturnCode_t {
    OK
    FormatError
    UnknownCommand
    Busy
    IncorrectState
    InvalidSubunitNumber
    InvalidSubunitType
    NotAuthorized
    DataReadOnly
    InvalidLogicalArrayNumber
    GeneralError
}
}
```

#### Primary pseudocode:

*(This section is intentionally left blank)*

#### ALD pseudocode:

```
UNLESS Cmd.LogicalArrayNumber IN LogicalArrayNumberList THEN
    RETURN InvalidLogicalArrayNumber
EXIT
ENDIF

IF ALDType = MALD THEN
    IF ActiveAuth[CurrentPort].Authority[Cmd.Subunit] = NoAccess THEN
        RETURN NotAuthorised
    EXIT
    ENDF
ENDIF

result ← IsCommandAllowed( LIST{ OperatingConnectionState},
                           Cmd.Command, CurrentPort)

UNLESS result.allowed THEN
    RETURN result.code
EXIT
ENDIF
```

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```
IF «Logical array numbers are read only in this RET subunit» THEN
    RETURN DataReadOnly
ELSE
    «Store the logical array numbers for the supplied Subunit to non-volatile memory»
    IF «the ALD detects a hardware error» THEN
        // Replace "Hardware error" with descriptive text to be read using
        // GetDiagnosticInformation
        RAISE AlarmGeneralError SEVERITY Major ON Cmd.Subunit, "Hardware error"
        RETURN GeneralError
    ELSE
        RETURN OK
    ENDIF
ENDIF
CommandExit(Cmd.Command, CurrentPort)
EXIT
```

#### 11.4.6. RET Get Logical Array Numbers Of Subunit

##### Description (Informative):

This command returns the list of logical arrays the subunit is controlling.

##### Message format:

```
PrimaryCommand RETGetLogicalArrayNumbersOfSubunitCommand {
    CommandCode_t      Command ← 0x0105
    CommandSequence_t  PrimaryCommandSequence
    Subunit_t          Subunit
    DataLength_t       DataLength ← 0
}

ALDResponse RETGetLogicalArrayNumbersOfSubunitResponse {
    CommandCode_t      Command ← 0x0105
    CommandSequence_t  PrimaryCommandSequence
    ReturnCode_t       ReturnCode
    DataLength_t       DataLength
    if (ReturnCode == OK) {
        uint8_t         NrOfLogicalArrays
        uint16_t        LogicalArrayNumber[1..NrOfLogicalArrays]
    }
    else {
        ALDState_t      ALDState
        ConnectionState_t  ConnectionState
        RETCalState_t   RETCalState
        RETJamState_t   RETJamState
        RETMovingState_t  RETMovementState
    }
}
```

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## Subunit Type Standard AISG-ST-RET

### vRET3.1.3.0

11<sup>th</sup> June 2019



```
Enumeration ReturnCode_t {
    OK
    FormatError
    UnknownCommand
    Busy
    InvalidSubunitNumber
    InvalidSubunitType
    NotAuthorised
    IncorrectState
}
```

#### Primary pseudocode:

*(This section is intentionally left blank)*

#### ALD pseudocode:

```
IF ALDType = MALD
    AND ActiveAuth[CurrentPort].Authority[Cmd.Subunit] = NoAccess THEN
        RETURN NotAuthorised
    EXIT
ENDIF

result ← IsCommandAllowed( LIST{      OperatingConnectionState
                                   RestrictedConnectionState,
                                   MALDConfigConnectionState},
                           Cmd.Command, CurrentPort)

UNLESS result.allowed THEN
    RETURN result.code
    EXIT
ENDIF

RETURN OK, « number of stored logical arrays and the list of array numbers of requested
RET Subunit»
CommandExit(Cmd.Command, CurrentPort)
EXIT
```